Formulas for MathII Exam.

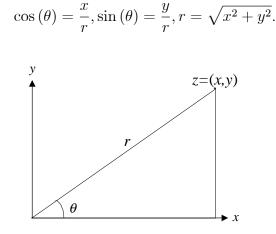
1. Complex numbers and trigonometric functions

Measured in radians we have $\sin(0) = 0$, $\cos(0) = 1$, $\sin(\pi/2) = 1$, $\cos(\pi/2) = 0$, $\sin(\pi) = 0$, $\cos(\pi) = -1$, $\sin(\frac{3\pi}{2}) = -1$, $\cos(\frac{3\pi}{2}) = 0$, $\frac{d\sin(x)}{dx} = \cos(x)$ and $\frac{d\cos(x)}{dx} = -\sin(x)$.

The formula for the solution to a quadratic equation $ax^2 + bx + c = 0$, is

$$x = -\frac{b}{2a} \pm \frac{\sqrt{b^2 - 4ac}}{2a}$$

In the right-angled triangle in the figure, we have



Let z be the complex number (x, y), then z satisfies $z = re^{i\theta}$ where r is the modulus of z and θ is the argument.

2. Differential equations.

For a linear differential equation with one of the roots given by r_n , the associated homogeneous solution is

$$y\left(t\right) = e^{r_{n}t}.$$

For a linear differential equation with a complex pair of roots $r_{1,2} = a \pm bi$, the associated

homogeneous solution is

$$y(t) = e^{at} \left(\bar{c}_1 \cos \left(bt \right) + \bar{c}_2 \sin \left(bt \right) \right).$$

For a linear differential equation with repeated roots $r_1, ... r_k$ all equal to r, the associated homogeneous solution is

$$y(t) = c_1 e^{rt} + c_2 t e^{rt} + \dots + c_k t^{k-1} e^{rt}.$$

For the homogeneous linear system of differential equations,

$$\begin{bmatrix} \dot{y}_{1}(t) \\ \dot{y}_{2}(t) \end{bmatrix} = \mathbf{A} \begin{bmatrix} y_{1}(t) \\ y_{2}(t) \end{bmatrix},$$

where A is assumed to have distinct eigenvalues different from zero, the solution is

$$\begin{bmatrix} y_1(t) \\ y_2(t) \end{bmatrix} = \mathbf{B}^{-1} \begin{bmatrix} e^{r_1 t} & 0 \\ 0 & e^{r_2 t} \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \end{bmatrix}$$

where \mathbf{B}^{-1} is the matrix of eigenvectors of \mathbf{A} and r_1 and r_2 are the eigenvalues of \mathbf{A} .

3. Difference equations

For a linear differential equation with one of the roots given by r_n , the associated homogeneous solution is

$$x_t = c_1 r_1^t.$$

For a linear differential equation with a pair of complex roots given by $r_{1,2} = a \pm bi$, the associated homogeneous solution is

$$x_t = |r|^t \left(\tilde{c}_1 \cos t\theta + \tilde{c}_2 \sin t\theta \right)$$

where $|r| = \sqrt{a^2 + b^2}$ and $\theta = \tan^{-1} \frac{b}{a}$.

For a linear differential equation with repeated roots $r_1, ..., r_k$, all equal to r, the associated homogeneous solution is

$$x_t = r^t \left(c_1 + tc_2 + \dots + t^{k-1}c_k \right).$$

For the homogeneous linear system of differential equations,

$$\left[egin{array}{c} y_{1,t+1} \ y_{2,t+1} \end{array}
ight] = {f A} \left[egin{array}{c} y_{1,t} \ y_{2,t} \end{array}
ight],$$

where A is assumed to have distinct eigenvalues different from zero, the solution is

$$\begin{bmatrix} y_{1,t+1} \\ y_{2,t+1} \end{bmatrix} = \mathbf{B}^{-1} \begin{bmatrix} r_1^t & 0 \\ 0 & r_2^t \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \end{bmatrix}$$

4. Linear algebra

The eigenvalues of a matrix

$$\mathbf{A} \equiv \left[\begin{array}{cc} a_{11} & a_{12} \\ \\ a_{21} & a_{22} \end{array} \right]$$

 are

$$r_{1,2} = \frac{a_{11} + a_{22} \pm \sqrt{\left(a_{11} - a_{22}\right)^2 + 4a_{12}a_{21}}}{2}.$$

If r_i is an eigenvalue of **A**, the associated eigenvector \mathbf{e}_i satisfies

$$\mathbf{A}\mathbf{e}_i = r_i\mathbf{e}_i.$$

The inverse of the matrix is given by

$$\begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix}^{-1} = \frac{1}{a_{11}a_{22} - a_{12}a_{21}} \begin{bmatrix} a_{22} & -a_{12} \\ -a_{21} & a_{11} \end{bmatrix}.$$